

# Solving the Polynomial Eigenvalue Problem by Linearization

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# Outline

PEP and Linearization Background

B'err and Conditioning of Linearizations

Algorithm based on Linearization

# Polynomial Eigenproblem (PEP)

$$P(\lambda) = \sum_{i=0}^m \lambda^i A_i, \quad A_i \in \mathbb{C}^{n \times n}, \quad A_m \neq 0.$$

$P$  assumed **regular** ( $\det P(\lambda) \neq 0$ ).

Find scalars  $\lambda$  and nonzero vectors  $x$  and  $y$  satisfying  $P(\lambda)x = 0$  and  $y^* P(\lambda) = 0$ .

Special case quadratic eigenvalue problem (QEP):

$$(\lambda^2 M + \lambda D + K)x = 0.$$

# Applications

- ▶ classical structural mechanics
- ▶ molecular dynamics
- ▶ gyroscopic systems
- ▶ optical waveguide design
- ▶ MIMO systems in control theory
- ▶ constrained least squares problems.

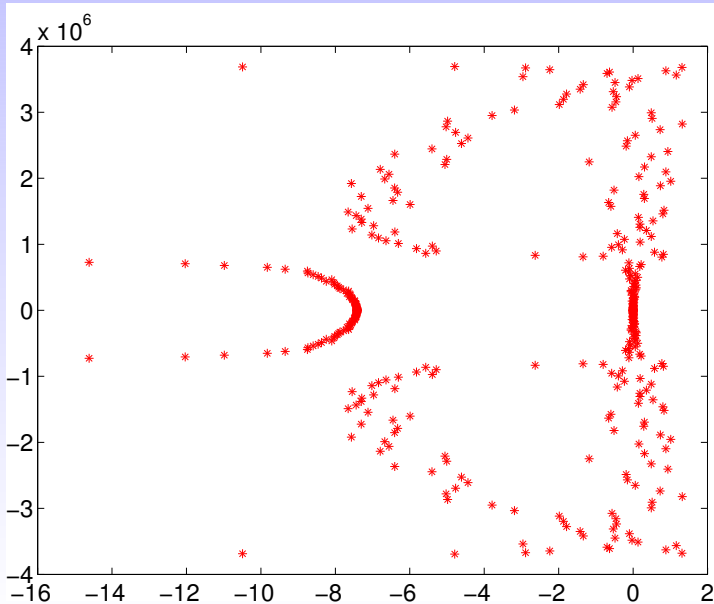
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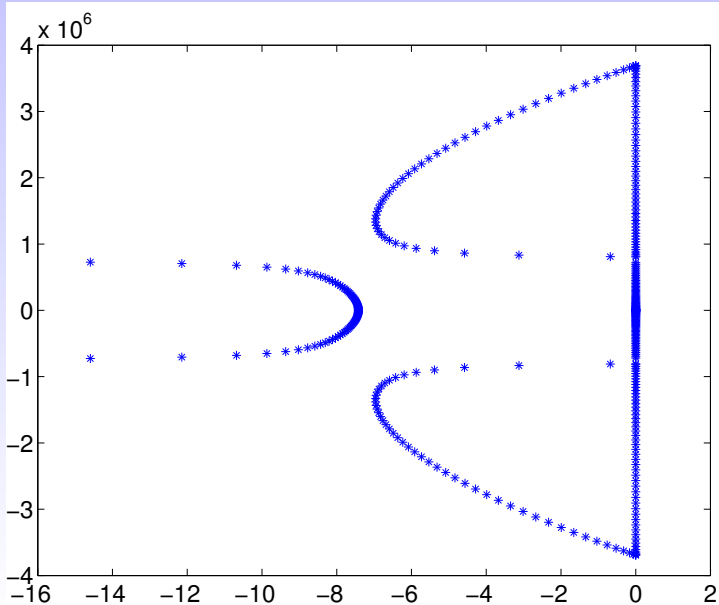
More specifically:

- ▶ Vibration of rail tracks by high speed trains (SIAM News, Nov. 2004).
- ▶ Extreme designs lead to problems with poor conditioning; physics of system leads to structure.

# Polyeig (Companion Pencil)



# Polyeig on Scaled Quadratic



# Methods

Interested in methods for solving dense problems (possibly a projection of a sparse problem).

- ▶ Solvent:  $\sum_{i=0}^m A_i X^i = 0$ .
- ▶ Bandwidth reduction.
- ▶ Structure-preserving transformations.
- ▶ **Linearization.**



# Current Software

- ▶ MATLAB's **polyeig**.
- ▶ Solvers in commercial engineering packages (Nastran, etc.).

**Aim to design and implement LAPACK solvers for *general and structured* QEPs/PEPs (Manchester and TU Berlin).**

# Linearizations

$$L(\lambda) = \lambda X + Y, \quad X, Y \in \mathbb{C}^{mn \times mn}$$

is a **linearization** of  $P(\lambda) = \sum_{i=0}^m \lambda^i A_i$  if

$$E(\lambda)L(\lambda)F(\lambda) = \begin{bmatrix} P(\lambda) & 0 \\ 0 & I_{(m-1)n} \end{bmatrix}$$

for some **unimodular**  $E(\lambda)$  and  $F(\lambda)$ .

## Example

Companion form linearization

$$E(\lambda) \left( \lambda \begin{bmatrix} A_2 & 0 \\ 0 & I \end{bmatrix} + \begin{bmatrix} A_1 & A_0 \\ -I & 0 \end{bmatrix} \right) F(\lambda) = \begin{bmatrix} \lambda^2 A_2 + \lambda A_1 + A_0 & 0 \\ 0 & I \end{bmatrix}.$$

# Solution Process for PEP

- ▶ **Linearize**  $P(\lambda)$  into  $L(\lambda) = \lambda X + Y$ .
- ▶ Solve **generalized eigenproblem**  $L(\lambda)z = 0$ .
- ▶ **Recover** eigenvectors of  $P$  from those of  $L$ .

Usual choice of  $L$ : companion linearization, for which

$$z = \begin{bmatrix} \lambda^{m-1} x \\ \vdots \\ \lambda x \\ x \end{bmatrix}.$$

Left e'vec: more complicated formula.

# Desiderata for a Linearization

- ▶ Good conditioning.
- ▶ Backward stability.
- ▶ Suitable **eigenvector recovery** formulae.
- ▶ Preservation of structure, e.g. **symmetry**.
- ▶ Numerical preservation of key **qualitative** properties, including location and symmetries of spectrum.
- ▶ Preserve partial multiplicities of e'vals (strong linearization).

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# Backward Error

$$P(\alpha, \beta) = \sum_{i=0}^m \alpha^i \beta^{m-i} \mathbf{A}_i \quad (\lambda \equiv \alpha/\beta).$$

$(\mathbf{x}, \alpha, \beta)$  approx eigenpair of  $P$ :

$$\eta_P(\mathbf{x}, \alpha, \beta) = \min \left\{ \epsilon : \sum_{i=0}^m \alpha^i \beta^{m-i} (\mathbf{A}_i + \Delta \mathbf{A}_i) \mathbf{x} = 0, \right. \\ \left. \|\Delta \mathbf{A}_i\|_2 \leq \epsilon \|\mathbf{A}_i\|_2, \quad i = 0 : m \right\}.$$

Extending Tisseur (2000):

$$\eta_P(\mathbf{x}, \alpha, \beta) = \frac{\|P(\alpha, \beta)\mathbf{x}\|_2}{\left(\sum_{i=0}^m |\alpha|^i |\beta|^{m-i} \|\mathbf{A}_i\|_2\right) \|\mathbf{x}\|_2}.$$

# Key Question

★ How **good** an **approx eigenpair** of  $P$  will be produced from an approx eigenpair of  $L$ ?

Here “good” refers to

- relative error (see H, D. S. Mackey & Tisseur, 2005),
- backward error.

A small perturbation to

$$C_1(\lambda) = \begin{bmatrix} A_2 & 0 \\ 0 & I \end{bmatrix} + \begin{bmatrix} A_1 & A_0 \\ I & 0 \end{bmatrix}$$

may not correspond to a small perturbation to

$$Q(\lambda) = \lambda^2 A_2 + \lambda A_1 + A_0.$$

## Want to compare

$$\eta_P(\mathbf{x}, \alpha, \beta) = \frac{\|P(\alpha, \beta)\mathbf{x}\|_2}{\left(\sum_{i=0}^m |\alpha|^i |\beta|^{m-i} \|A_i\|_2\right) \|\mathbf{x}\|_2},$$

with

$$\eta_L(\mathbf{z}, \alpha, \beta) = \frac{\|L(\alpha, \beta)\mathbf{z}\|_2}{(|\alpha|\|\mathbf{X}\|_2 + |\beta|\|\mathbf{Y}\|_2)\|\mathbf{z}\|_2}.$$

$(\mathbf{z}, \alpha, \beta)$ : **approx** e'pair of linearization  $L(\lambda) = \lambda\mathbf{X} + \mathbf{Y}$  of  $P(\lambda)$ .

$(\mathbf{x}, \alpha, \beta)$ : **approx** e'pair of  $P$  with  $\mathbf{x}$  **recovered from**  $\mathbf{z}$ .



# One Sided Factorization

Suppose there exists  $n \times nm$   $G(\alpha, \beta)$  s.t.

$$G(\alpha, \beta)L(\alpha, \beta) = g^T \otimes P(\alpha, \beta), \quad g \in \mathbb{C}^m.$$

With  $z_i := z((i-1)n+1:in)$ ,

$$\begin{aligned} G(\alpha, \beta)L(\alpha, \beta)z &= (g^T \otimes P(\alpha, \beta))z \\ &= [g_1 P(\alpha, \beta) \quad \dots \quad g_m P(\alpha, \beta)] \begin{bmatrix} z_1 \\ \vdots \\ z_m \end{bmatrix} \\ &= P(\alpha, \beta) \sum_{i=1}^m g_i z_i =: P(\alpha, \beta)x. \end{aligned}$$

$$\Rightarrow \|P(\alpha, \beta)x\|_2 \leq \|G(\alpha, \beta)\|_2 \|L(\alpha, \beta)z\|_2.$$

## Bounding $\eta_P/\eta_L$

Suppose  $G(\alpha, \beta)L(\alpha, \beta) = \mathbf{g}^T \otimes P(\alpha, \beta)$ ,  $\mathbf{g} \in \mathbb{C}^m$ .

Let  $\mathbf{z}$  be approx e'vec of  $L$  with e'val  $(\alpha, \beta)$  and take  $\mathbf{x} = \sum g_i \mathbf{z}_i$  as approx e'vec of  $P$ .

$$\frac{\eta_P(\mathbf{x}, \alpha, \beta)}{\eta_L(\mathbf{z}, \alpha, \beta)} = \frac{|\alpha| \|\mathbf{X}\|_2 + |\beta| \|\mathbf{Y}\|_2}{\sum_{i=0}^m |\alpha|^i |\beta|^{m-i} \|\mathbf{A}_i\|_2} \cdot \frac{\|P(\alpha, \beta)\mathbf{x}\|_2}{\|L(\alpha, \beta)\mathbf{z}\|_2} \cdot \frac{\|\mathbf{z}\|_2}{\|\mathbf{x}\|_2}.$$

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$$\frac{\eta_P(x, \alpha, \beta)}{\eta_L(z, \alpha, \beta)} \leq \frac{|\alpha| \|X\|_2 + |\beta| \|Y\|_2}{\sum_{i=0}^m |\alpha|^i |\beta|^{m-i} \|A_i\|_2} \cdot \frac{\|G(\alpha, \beta)\|_2 \|z\|_2}{\|x\|_2}.$$

- **Separates the dependence** on  $L$ ,  $P$  and  $(\alpha, \beta)$  from dependence on  $G$  and  $z$ .
- $\eta_P$  is **finite** if  $\eta_L$  is.

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- $\eta_P$  is **finite** if  $\eta_L$  is.
- Sim. for left e'vecs: assume

$$L(\alpha, \beta)H(\alpha, \beta) = h \otimes P(\alpha, \beta), \quad h \in \mathbb{C}^m.$$

# Vector Spaces $\mathbb{L}_1$ , $\mathbb{L}_2$ , and $\mathbb{DL}(P)$

$$\Lambda := [\lambda^{m-1}, \lambda^{m-2}, \dots, 1]^T.$$

Mackey, Mackey, Mehl & Mehrmann (2005) define

$$\mathbb{L}_1(P) = \{ L(\lambda) : L(\lambda)(\Lambda \otimes I_n) = \mathbf{v} \otimes P(\lambda), \mathbf{v} \in \mathbb{C}^m \},$$

$$\mathbb{L}_2(P) = \{ L(\lambda) : (\Lambda^T \otimes I_n)L(\lambda) = \tilde{\mathbf{v}}^T \otimes P(\lambda), \tilde{\mathbf{v}} \in \mathbb{C}^m \},$$

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- Dimensions:  $\mathbb{L}_1, \mathbb{L}_2: m(m-1)n^2 + m$ ,  $\mathbb{DL}: m$ .
- Pencils in  $\mathbb{DL}(P)$  are block symmetric.
- Almost all  $L$  in the above are linearizations.

# Companion Linearizations

$$C_i(\lambda) = \lambda X + Y_i \text{ with } X = \text{diag}(A_m, I_n, \dots, I_n),$$

$$Y_1 = \begin{bmatrix} A_{m-1} & A_{m-2} & \dots & A_0 \\ -I_n & 0 & \dots & 0 \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \dots & -I_n & 0 \end{bmatrix}, \quad Y_2 = \begin{bmatrix} A_{m-1} & -I_n & \dots & 0 \\ A_{m-2} & 0 & \ddots & \vdots \\ \vdots & \vdots & \ddots & -I_n \\ A_0 & 0 & \dots & 0 \end{bmatrix}.$$

- $C_1 \in \mathbb{L}_1(P)$  ( $v = e_1$ ) and  $C_2 \in \mathbb{L}_2(P)$  ( $\tilde{v} = e_1$ ).
- $C_1$  and  $C_2$  *always* (strong) linearizations.
- $C_2(P) = C_1(P^T)^T \Rightarrow$  concentrate on  $C_1$  only.

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- $C_1$  and  $C_2$  *always* (strong) linearizations.
- $C_2(P) = C_1(P^T)^T \Rightarrow$  concentrate on  $C_1$  only.

## Are the factorizations

$$G(\alpha, \beta)C_1(\alpha, \beta) = g^T \otimes P(\alpha, \beta),$$

$$C_1(\alpha, \beta)H(\alpha, \beta) = h \otimes P(\alpha, \beta)$$

possible for  $C_1$ ?



# First Companion

- ▶ For  $m = 2$ ,

$$\begin{bmatrix} \alpha I & -\beta A_0 \\ \beta I & \beta A_1 + \alpha A_2 \end{bmatrix} C_1(\alpha, \beta) = \begin{bmatrix} P(\alpha, \beta) & 0 \\ 0 & P(\alpha, \beta) \end{bmatrix}$$

yields two choices:

$$\begin{aligned} G(\alpha, \beta) &= [\alpha I \quad -\beta A_0], & g &= e_1 \Rightarrow x = z_1, \\ G(\alpha, \beta) &= [\beta I \quad \beta A_1 + \alpha A_2], & g &= e_2 \Rightarrow x = z_2. \end{aligned}$$

*Generalizes to arbitrary degrees  $m$ .*

- ▶  $C_1 \in \mathbb{L}_1$  ( $v = e_1$ )  $\Rightarrow C_1(\alpha, \beta)(\Lambda_{\alpha, \beta} \otimes I_n) = e_1 \otimes P(\alpha, \beta)$ .  
Can take  $H(\alpha, \beta) = \Lambda_{\alpha, \beta} \otimes I_n$  and  $h = e_1 \Rightarrow y = w_1$ .

# First Companion: Right Eigenvector

## Theorem

Let  $z$  be approx right e'vec of  $C_1$  with approx e'val  $(\alpha, \beta)$ .  
 For  $\mathbf{z}_k = z((k-1)n+1:kn)$ ,  $k = 1:m$ ,

$$\frac{\eta_P(\mathbf{z}_k, \alpha, \beta)}{\eta_{C_1}(z, \alpha, \beta)} \leq m^{5/2} \frac{\max(1, \max_i \|A_i\|_2)^2 \|z\|_2}{\min(\|A_0\|_2, \|A_m\|_2) \|\mathbf{z}_k\|_2}.$$

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$\eta_P \approx \eta_{C_1}$  if

- ▶  $\min(\|A_0\|_2, \|A_m\|_2) \approx \max_i \|A_i\|_2 \approx 1$ .
- ▶  $\|z\|_2 / \|z_k\|_2 \approx 1$ .

$$\text{Exact } z = \Lambda_{\alpha, \beta} \otimes x \Rightarrow \frac{\|z\|_2}{\|z_k\|_2} \leq \sqrt{m}, \quad k = \begin{cases} 1 & \text{if } |\alpha| \geq |\beta|, \\ m & \text{if } |\alpha| \leq |\beta|. \end{cases}$$

# First Companion: Left Eigenvector

## Theorem

Let  $w$  be approx left e'vec of  $C_1$  with approx e'val  $(\alpha, \beta)$ .  
Then for  $w_1 = w(1:n)$ ,

$$\frac{\eta_P(w_1^*, \alpha, \beta)}{\eta_{C_1}(w^*, \alpha, \beta)} \leq m^{3/2} \frac{\max(1, \max_i \|A_i\|_2)}{\min(\|A_m\|_2, \|A_0\|_2)} \frac{\|w\|_2}{\|w_1\|_2}.$$

$\eta_P(w_1^*, \alpha, \beta) \approx \eta_{C_1}(w^*, \alpha, \beta)$  if

- ▶  $\min(\|A_0\|_2, \|A_m\|_2) \approx \max_i \|A_i\|_2 \approx 1$
- ▶  $\|w\|_2 / \|w_1\|_2 \approx 1$ .

# Left Eigenvector recovery for $C_1$

## Lemma

$y \in \mathbb{C}^n$  is a left e'vec of  $P$  with simple e'val  $(\alpha, \beta)$  iff

$$w = \begin{bmatrix} [\alpha^{m-1} \beta]^* \\ -[\alpha^{m-2} \beta A_{m-2} + \cdots + \alpha \beta^{m-2} A_1 + \beta^{m-1} A_0]^* \\ -[\alpha^{m-2} \beta A_{m-3} + \cdots + \alpha^2 \beta^{m-3} A_1 + \alpha \beta^{m-2} A_0]^* \\ \vdots \\ -[\alpha^{m-2} \beta A_0]^* \end{bmatrix} y, \quad \alpha \neq 0,$$

is a left e'vec of  $C_1$  corr. to  $(\alpha, \beta)$ . Every left e'vec of  $C_1$  with e'val  $(\alpha, \beta)$  has this form for some left e'vec  $y$  of  $P$ .

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If  $\|A_i\|_2 \approx 1 \ \forall i$  then exact left e'vec  $w$  satisfies  
 $\|w\|_2 / \|w_1\|_2 \leq (m^2/3)^{1/2}$ .

# UnScaled Companion Form

$$C_1(\lambda) = \lambda X + Y_i \text{ with } X = \text{diag}(A_m, I_n, \dots, I_n),$$

$$Y_1 = \begin{bmatrix} A_{m-1} & A_{m-2} & \dots & A_0 \\ -I_n & 0 & \dots & 0 \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \dots & -I_n & 0 \end{bmatrix}.$$



## Scaled Companion Form

$$C_1(\lambda) = \lambda X + Y_i \text{ with } X = \text{diag}(A_m, \mu I_n, \dots, \mu I_n),$$

$$Y_1 = \begin{bmatrix} A_{m-1} & A_{m-2} & \dots & A_0 \\ -\mu I_n & 0 & \dots & 0 \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \dots & -\mu I_n & 0 \end{bmatrix}.$$

Let  $D_\mu = \text{diag}(1, \mu, \dots, \mu) \otimes I_n$ , where  $\mu = \max_i \|A_i\|_2$ .  
Then  $D_\mu C_1(\lambda) \in \mathbb{L}_1(P)$  with  $v = e_1$ .

# Scaled Companion: Right and Left E'vecs

$$\rho = \frac{\max_i \|A_i\|_2}{\min(\|A_0\|_2, \|A_m\|_2)}.$$

## Theorem

*Let  $z$  and  $w$  be approx right and left e'vecs of  $D_\mu C_1$  corr. to the approx e'val  $(\alpha, \beta)$ . Then*

$$\frac{\eta_P(z_k, \alpha, \beta)}{\eta_{D_\mu C_1}(z, \alpha, \beta)} \leq m^{5/2} \rho \frac{\|z\|_2}{\|z_k\|_2}, \quad k = 1 : m,$$

$$\frac{\eta_P(w_1^*, \alpha, \beta)}{\eta_{D_\mu C_1}(w^*, \alpha, \beta)} \leq m^{3/2} \rho \frac{\|w\|_2}{\|w_1\|_2}.$$

# Comments

- Square has gone from right e'vec bound.
- Bounds now scale-independent ( $A_i \leftarrow \theta A_i$ ).
- $\|w\|_2 / \|w_1\|_2 \approx 1$  now guaranteed for all  $\|A_i\|_2$ .
- More sophisticated scalings, including balancing, may destroy  $\mathbb{L}_1$  property.

## Scaling $Q(\lambda)$

Write  $a = \|A\|_2$ ,  $b = \|B\|_2$ ,  $c = \|C\|_2$ .

Fan, Lin & Van Dooren (2004): let  $\lambda = \mu\gamma$ ,

$$Q(\lambda) = \lambda^2 A + \lambda B + C \rightarrow \tilde{Q}(\mu) = \mu^2(\delta\gamma^2 A) + \mu(\delta\gamma B) + \delta C,$$

where

$$\gamma = \sqrt{c/a}, \quad \delta = 2/(c + b\gamma).$$

For  $\tilde{Q}(\mu) = \mu^2 \tilde{A} + \mu \tilde{B} + \tilde{C}$  we have

$$\max(\|\tilde{A}\|_2, \|\tilde{B}\|_2, \|\tilde{C}\|_2) \leq 2.$$

# Growth Factor Bound

$$\frac{\eta_{\tilde{Q}}(z_i, \alpha, \beta)}{\eta_{C_1}(z, \alpha, \beta)} \leq 2^{7/2} \omega \frac{\|z\|_2}{\|z_i\|_2}, \quad i = 1, 2,$$

where, with  $|\alpha|^2 + |\beta|^2 = 1$ ,

$$1 \leq \omega \leq \min \left\{ 1 + \tau, \frac{1}{|\alpha\beta|} \right\} \leq 1 + \tau, \quad \tau = \frac{b}{\sqrt{ac}}.$$

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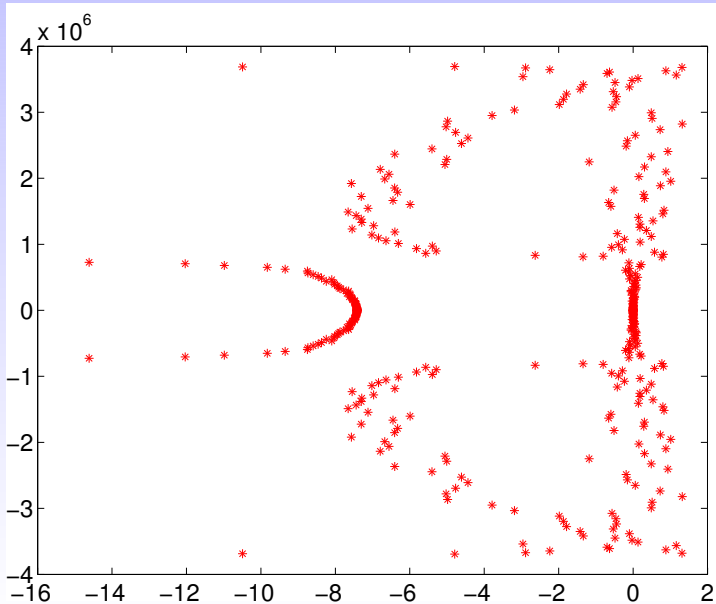
- ▶ F, L & VD identify  $\max(1 + \tau, 1 + \tau^{-1})$  as growth factor.
- ▶ Our bounds for  $\omega$  sharper:
  - $\tau \ll 1$  is harmless.
  - if  $\tau \gg 1$ ,  $\min\{\cdot\} = O(1)$  if  $|\alpha||\beta| = O(1)$ .
- ▶  $\omega = O(1)$  if  $\|B\|_2 \lesssim \sqrt{\|A\|_2 \|C\|_2}$ . Hence  $\eta_L \approx \eta_P$  for systems not heavily damped.

# Comparison with Conditioning Results

- ▶ Analysis of H, D. S. Mackey & Tisseur (2005) bounds the ratio  $\kappa_{C_1}(\alpha, \beta) / \kappa_P(\alpha, \beta)$ .
- ▶ Conditions for those  $\kappa_{C_1}(\alpha, \beta) \approx \kappa_P(\alpha, \beta)$  are *“essentially the same”* as those for  $\eta_{C_1} \approx \eta_P$ .

**Backward error results entirely harmonious with e'val conditioning results.**

# Polyeig (Companion Pencil)







# Details

	Before scaling	After scaling
$\ A\ _2$	$10^{-2}$	$10^0$
$\ B\ _2$	$10^0$	$10^{-3}$
$\ C\ _2$	$10^9$	$10^0$
	$\rho = 10^{11}$	$\rho = 1, \omega = 1$

# Outline

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Algorithm based on Linearization

# Meta-Algorithm for PEP

- 1 **Preprocess  $P$**
- 2 **for** one or more (scaled) linearizations  $L$
- 3 **Balance  $L$**
- 4 Apply QZ to  $L$  (maybe HZ if structured)
- 5 Obtain relevant e'vals
- 6 Recover left and right e'vecs
- 7 **Iteratively refine e'vecs**
- 8 Compute/estimate b'errs and condition numbers
- 9 Detect nonregular problem
- 10 **end**

# Balancing

Balancing GEP:

- ▶ Ward (1981)
- ▶ Lemonnier & Van Dooren (2005)

To investigate:

- Exploit structure of pencils arising via linearization of a matrix poly.
- Can we balance a QEP?
- To what extent can balancing make the results worse?  
Cf. Watkins (2006): *A Case where Balancing is Harmful.*

# Iterative Refinement

- ▶ Underlying theory for fixed and extended precision residuals in Tisseur (2001).
- ▶ Done for definite GEPs in Davies, H & Tisseur (2001).
- ▶ Details for QEPs in Berhanu (2005), incl. complex conj. pairs in real arith.

## Issues:

- Convergence to wrong eigenpair or non-convergence.
- Exploiting structure of pencil from a linearization.

# *Tentative* Outline of Algorithm for QEP

- 1 Preprocess  $Q$ : Fan, Lin & Van Dooren (2004) scaling
- 2 Let  $L = D_{\mu}C_1$ : scaled companion linearization
- 3 Apply QZ to  $L$
- 4 Obtain relevant e'vals
- 5 Recover left ( $w_1$ ) and right ( $\max_i \|z_i\|_2$ ) e'vecs
- 6 Compute/estimate b'errs and condition numbers
- 7 Detect nonregular problem

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Main **polyeig** differences:

- ▶ Doesn't scale.
- ▶ Doesn't return left e'vecs.
- ▶ Doesn't detect nonregular  $Q$ .



# Concluding Remarks

- ★ Analysis of cond. & b'err for wide variety of lineariz'ns.
- ★ E'vector recovery formulae *crucial*.
- ★ Scaling *crucial*.
- ★ Favour  $L =$  (scaled) companion form for general PEPs.
- ★  $L \in \mathbb{L}_1(P), \mathbb{L}_2(P)$  or  $\mathbb{DL}(P)$  for structured problems.
- ★ Poised to develop a general PEP algorithm & code.
- ★ Further work needed on
  - ★ algorithmics
  - ★ scaling & balancing (pencils & general  $m$ )
  - ★ structured problems (symm, odd–even, definite)
  - ★ ...

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