

FIXED-POINT ITERATION

Seek x_* such that $g(x_*) = x_*$ for $g: \mathbb{R}^n \rightarrow \mathbb{R}^n$:

$$x_{k+1} = g(x_k), \quad k \geq 1, \quad x_0 \in \mathbb{R}^n \text{ given.}$$

ANDERSON ACCELERATION (BASIC)

The iteration history for some chosen $m \geq 0$ is

$$\begin{array}{cccccc} \dots & x_{k-m} & x_{k-(m-1)} & \dots & x_{k-1} & x_k \\ \dots & g(x_{k-m}) & g(x_{k-(m-1)}) & \dots & g(x_{k-1}) & g(x_k) \end{array}$$

► Define x_{k+1} using **all** this information; [ANDERSON 1965].

Given $x_0 \in \mathbb{R}^n$ and $m \geq 1$.

- 1 $x_1 = g(x_0)$.
- 2 For $k = 1, 2, \dots$
- 3 $m_k = \min\{m, k\}$.
- 4 Compute $\theta^{(k)}$ solving $\min_{\theta \in \mathbb{R}^{m_k}} \|v_k - u_k\|_2^2$, where

$$u_k = x_k + \sum_{j=1}^{m_k} \theta_j (x_{k-j} - x_k),$$

$$v_k = g(x_k) + \sum_{j=1}^{m_k} \theta_j (g(x_{k-j}) - g(x_k)).$$

- 5 $x_{k+1} = v_k$ with the parameters from $\theta^{(k)}$.
- 6 end

■ If g linear and $m_k = k$, essentially GMRES.

ANDERSON ACCELERATION (PRACTICAL)

► **Equivalent version** designed for $f(x_*) = 0$; [FANG, SAAD 2009], [WALKER, NI 2011].

$$\mathcal{X}_k = [\Delta x_{k-m_k} \ \dots \ \Delta x_{k-1}] \in \mathbb{R}^{n \times m_k}, \quad \Delta x_i = x_{i+1} - x_i,$$

$$\mathcal{G}_k = [\Delta g_{k-m_k} \ \dots \ \Delta g_{k-1}] \in \mathbb{R}^{n \times m_k}, \quad \Delta g_i = g(x_{i+1}) - g(x_i),$$

$$\mathcal{F}_k = \mathcal{G}_k - \mathcal{X}_k, \quad f_k = g(x_k) - x_k.$$

Given $x_0 \in \mathbb{R}^n$ and $m \geq 1$.

- 1 $x_1 = g(x_0)$.
- 2 For $k = 1, 2, \dots$
- 3 $m_k = \min\{m, k\}$.
- 4 Compute $\gamma^{(k)}$ which solves $\min_{\gamma \in \mathbb{R}^{m_k}} \|f_k - \mathcal{F}_k \gamma\|_2^2$.
- 5 $x_{k+1} = g(x_k) - \mathcal{G}_k \gamma^{(k)}$.
- 6 end

LS PROBLEM DETAILS

At each iteration first col \mathcal{F}_k is removed and new last column added \Rightarrow **update QR factors of \mathcal{F}_k as iteration progresses**.

NEAREST CORRELATION MATRIX (NCM)

A **correlation matrix** is pos semidef with unit diagonal.

Given $A = A^T \in \mathbb{R}^{n \times n}$, compute

$$\min\{\|A - X\|_F : X \text{ a.c.m.}\}, \quad (1)$$

$$\min\{\|A - X\|_F : X \text{ a.c.m.}, \lambda_{\min}(X) \geq \delta, 0 < \delta \leq 1\}, \quad (2)$$

$$\min\{\|A - X\|_F : X \text{ a.c.m.}, x_{ij} = a_{ij} \text{ for } (i, j) \in \mathcal{N}\}. \quad (3)$$

For (1) and (2) solution is **unique**, for (3) unique **if it exists**.

APPLICATIONS INCLUDE

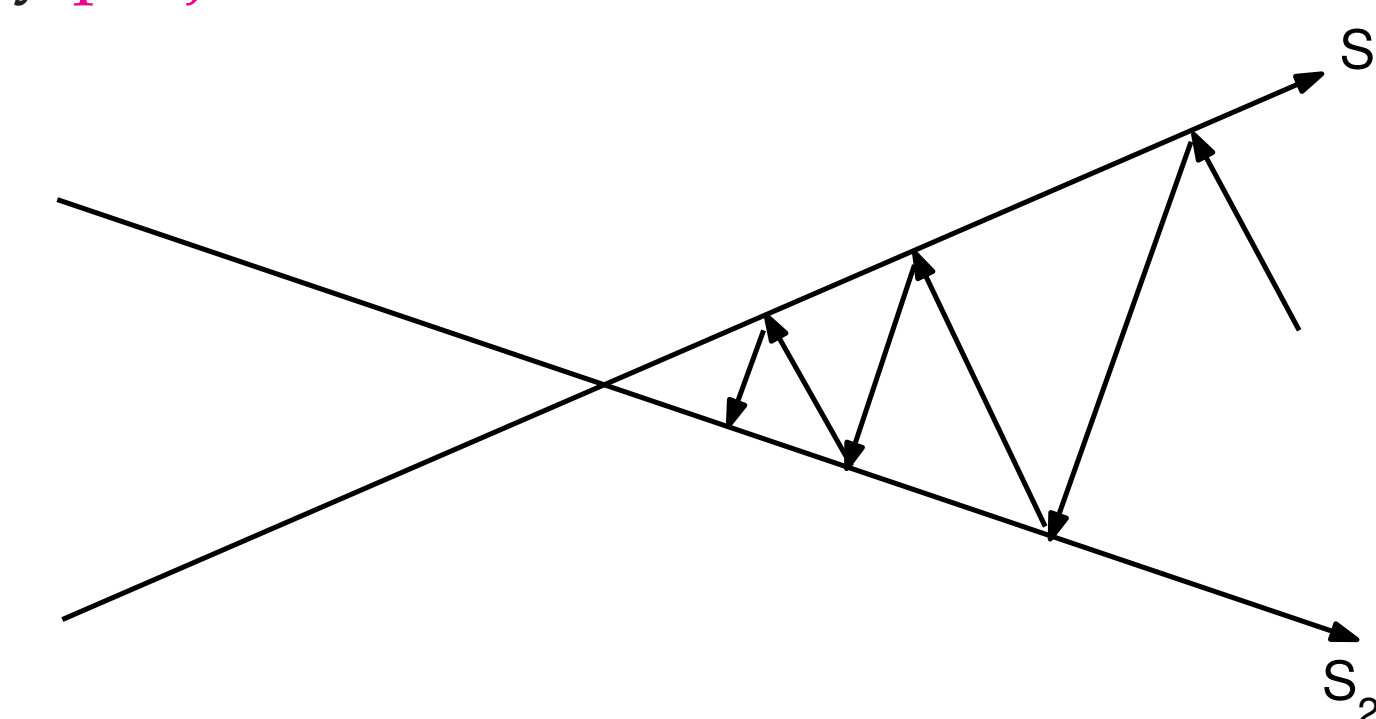
- Portfolio risk management in **finance**.
- Prediction of **electricity peak-demand**.
- Modelling **public health**.
- Simulation of **wireless links** in vehicular networks.
- Analysis of **carbon dioxide storage resources** in the US.
- Determination of **insurance premiums** for crops.
- **Genetic evaluations** for thoroughbred horse breeding.

ALTERNATING PROJECTIONS METHOD

- First method with **guaranteed convergence** (at best linear); [HIGHAM 2002].
- Widely implemented (MATLAB, Python, R, SAS).
- **Solves all three problems**.

NCM is the nearest matrix to A in the intersection of $S_1 = \text{symm pos semidef}$ and $S_2 = \text{symm unit diag}$.

Iteratively **project** onto sets.



Convergence results: [VON NEUMANN 1933] – for subspaces. [DYKSTRA 1983], [BOYLE, DYKSTRA 1986] – **corrections** for closed convex sets.

NEWTON METHOD

- **Global quadratic convergence**; [QI, SUN 2006].
- In NAG library with improvements [BORSDOFF, HIGHAM 2010].
- **Cannot** solve the fixed elements variant.

MOTIVATION FOR NCM PROBLEMS

Correlation matrix obtained in practice might be

- **Indefinite**, as a result of
 - Missing data.
 - Expert judgement.
 - Asynchronous data.
 - Aggregation methods.
- **Singular**: always when there are fewer observations than variables.

ALTERNATING PROJECTIONS FOR NCM

A fixed-point variant of the code:

- 1 $\Delta_0 = 0, Y_0 = A$
- 2 For $k = 1, 2, \dots$
- 3 $(Y_k, \Delta_k) = g(Y_{k-1}, \Delta_{k-1})$
- 4 end
- 5 Return Y_k .

where the function g is $(Y_k, \Delta_k) = g(Y_{k-1}, \Delta_{k-1})$

- 6 $R_k = Y_{k-1} - \Delta_{k-1}$
- 7 $X_k = \mathcal{P}_{S_1}(R_k)$
- 8 $\Delta_k = X_k - R_k$
- 9 $Y_k = \mathcal{P}_{S_2}(X_k)$.

Individual projections:

- $\mathcal{P}_{S_1}(A)$: set all $\lambda_i(A) < \delta$ to δ , where $0 \leq \delta \leq 1$.
- $\mathcal{P}_{S_2}(A)$: overwrite with corresponding fixed elements.

Stopping test: $\|Y_k - X_k\|_F \leq \text{tol} \|Y_k\|_F$.

ANDERSON ACCELERATION FOR NCM

To use NCM code with Anderson acceleration write matrices as vectors using the **vec** operator.

TIMINGS

Computing **positive definite** NCM with $\delta = 0.1$ (for Anderson acceleration, $m = 2$) for six RiskMetrics matrices of order 387.

Matrix	nearcorr		nearcorr_AA			
	it	t	itAA	t	t_apm	t_AA
1	1410	20.50	383	10.77	5.70	3.12
2	2100	33.93	513	15.83	8.52	4.56
3	1900	31.14	414	11.58	5.97	3.54
4	1586	29.06	369	12.83	7.09	3.54
5	1812	31.30	400	12.99	7.16	3.62
6	1794	29.08	393	11.63	6.20	3.40

- Speedups 2–3.
- LS solution is a minor cost.

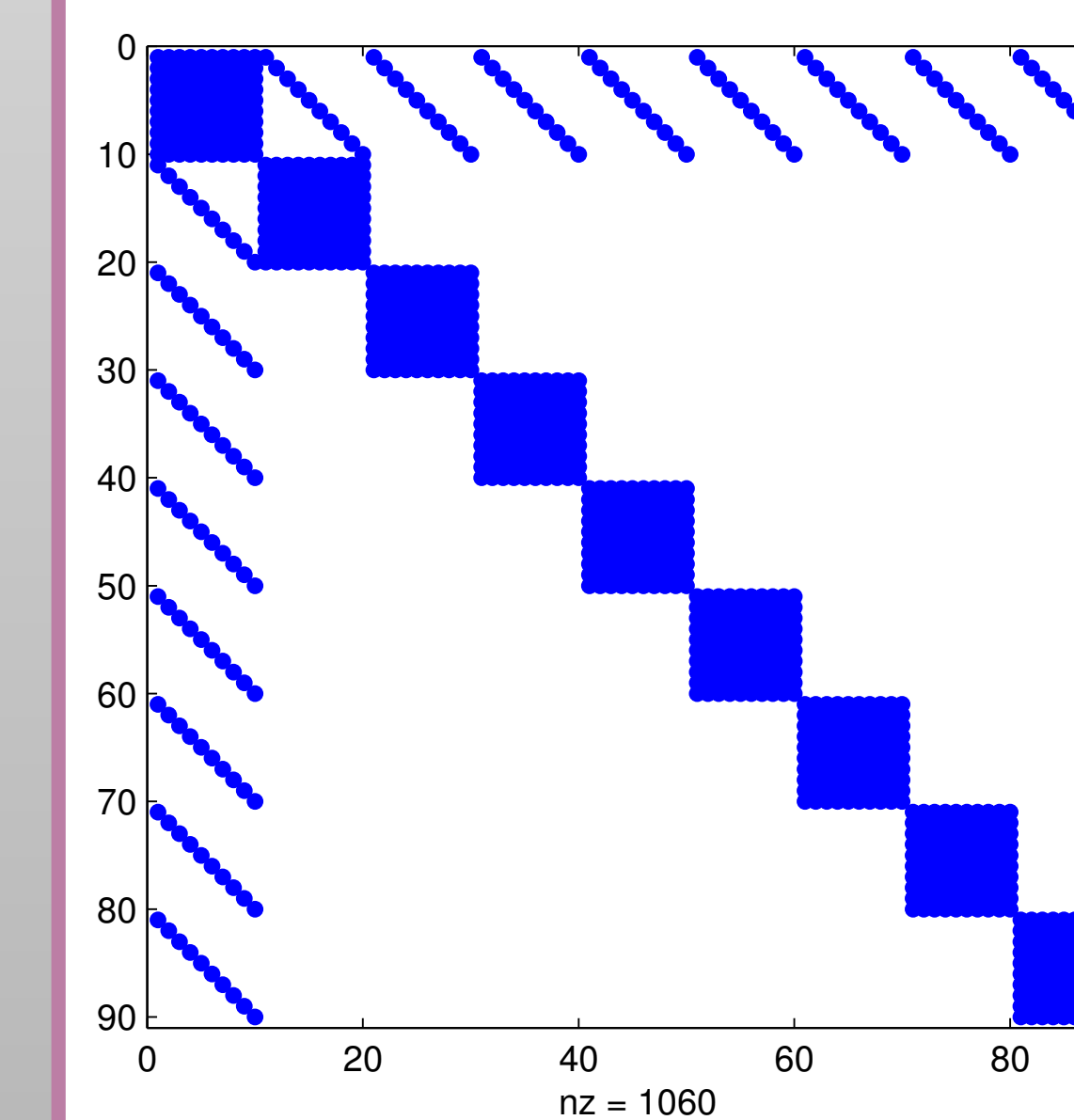
SMALL EXAMPLES

n	it	itAA					
		m = 1	m = 2	m = 3	m = 4	m = 5	m = 6
4	39	15	10	9	9	9	9
5	27	17	14	12	11	10	10
6	801	305	212	117	126	40	31
7	33	15	10	10	10	9	9

► Anderson acceleration reduces number of iterations for alternating projections method by **factor $\approx 3-25$** .

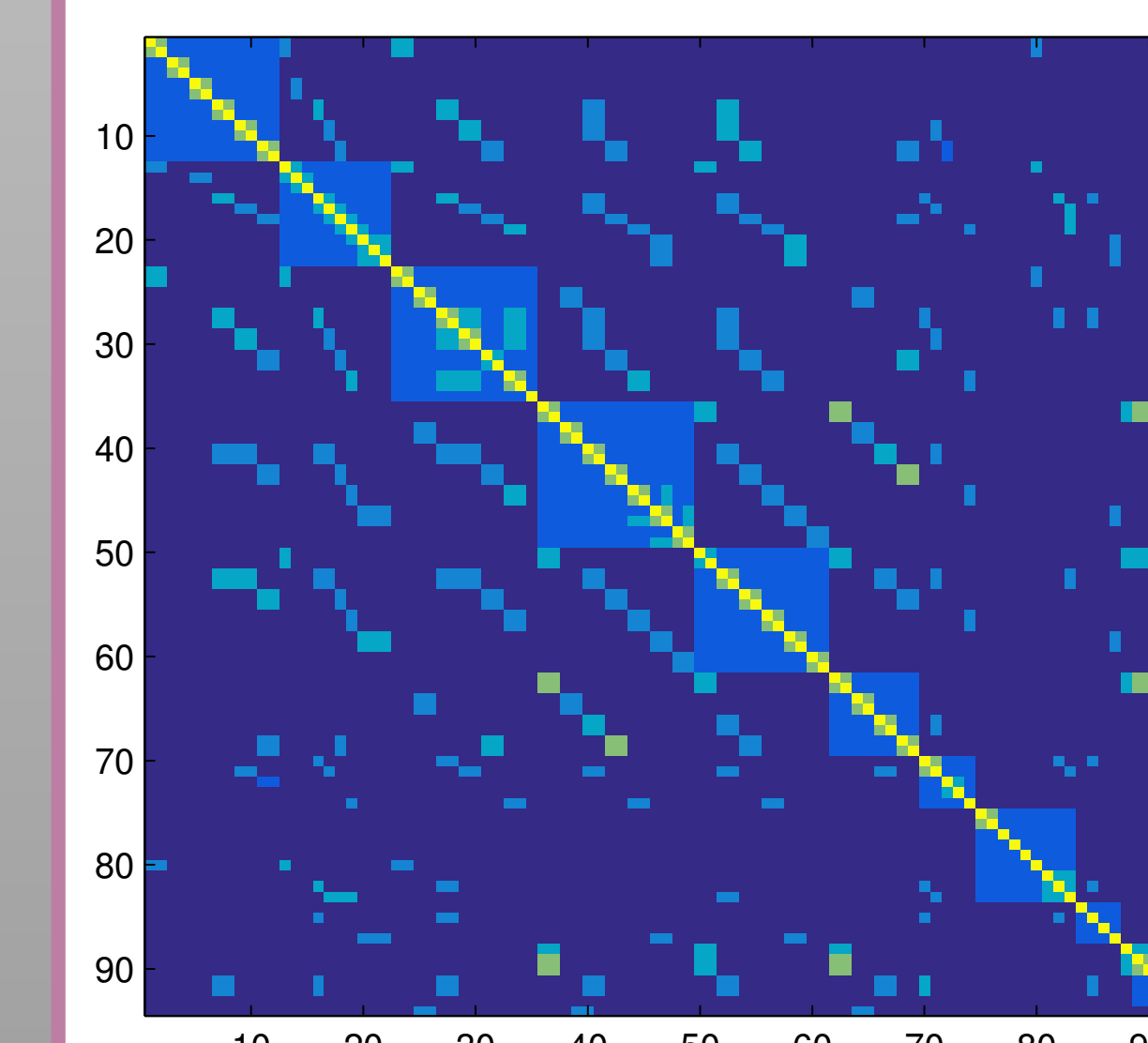
► Small values of m are sufficient.

FIXED ELEMENTS EXAMPLES



Keep fixed:

- (1,1) block.
- Main diagonal (not unit).
- "Small" diagonals.



Diag. blocks are fixed.

n	it	it_fe	itAA_fe				
			m = 1	m = 2	m = 3	m = 4	m = 5
90	29	169	93	70	55	45	39
94	18	40	15	14	12	12	12

► Additional constraints increase the iteration count.

► **Anderson acceleration remains effective**.

► For the variants, iterations reduce by **at least a third**.

REFERENCE

N. J. HIGHAM AND N. STRABIĆ. *Anderson acceleration of the alternating projections method for computing the nearest correlation matrix*. MIMS EPrint 2015.39, August 2015. 22 pp.