

$F(t)$ m

$\rightarrow x(t)$

$$m \frac{d^2 x}{dt^2} = F(t)$$

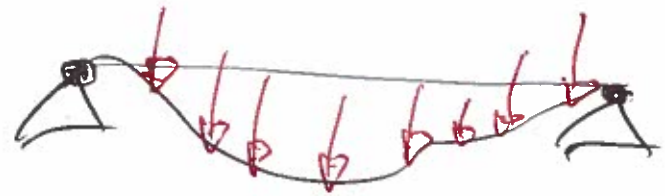
IC: $x(t=0) = x_0$

$$\left. \frac{dx}{dt} \right|_{t=0} = v_0$$

If $F(t) = F_0$:

$$x(t) = \frac{1}{2} \frac{F_0}{m} t^2 + v_0 t + x_0$$

(l) $P(x)$



$y \uparrow$
 $\rightarrow x$ $y = h(x)$

$$T \frac{d^2 h}{dx^2} = P(x)$$

BC: $h(x=0) = 0$

$$h(x=L) = 0$$

If $P(x) = P_0$

$$h(x) = \frac{1}{2} \frac{P_0}{T} (x^2 - Lx)$$

\Leftarrow & \Leftarrow "obvious"

IVP

BVP

finally, a counter-example: (2)

$$y' = y^{1/2} \quad y(0) = 0$$

one IC for a 1st order ODE



Spot 2 solns:

$$y = 0$$

and

$$y = \frac{1}{4} x^2$$

$$y' = \frac{1}{2} x ; \quad y^{1/2} = \frac{1}{2} x$$

$$y' \stackrel{?}{=} y^{1/2}$$

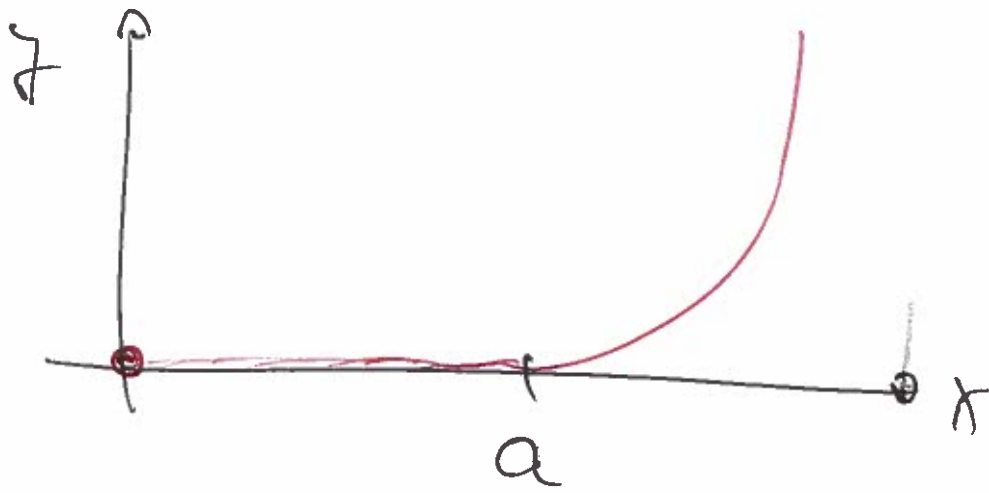
IC ✓



In fact:

$$y = \begin{cases} 0 & \text{for } 0 \leq x \leq a \\ \frac{1}{4}(x-a)^2 & \text{for } x > a \end{cases}$$

3



∞ many solutions!

Existence and uniqueness theorem for 1st order ODEs

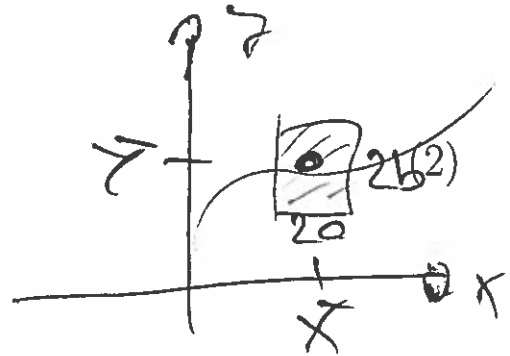
Consider the first-order ODE in its explicit form

$$\frac{dy}{dx} = f(x, y), \quad (1)$$

subject to the initial condition

$$y(X) = Y,$$

where the constants X and Y are given.



Theorem

If $f(x, y)$ and $\frac{\partial f(x, y)}{\partial y}$ are continuous functions of x and y in a region $0 < |x - X| < a$ and $0 < |y - Y| < b$, then there **exists exactly one** solution to the initial value problem defined by (1) and (2) in an interval $0 < |x - X| < h \leq a$.

Notes:

- The statement is easily generalised to higher-order ODEs.
- The theorem only provides a local statement!
- The statement only applies to initial value problems!
- The criteria listed are *sufficient* to ensure the existence of a unique solution but they are *not necessary*! \implies An IVP may still have a unique solution even if the conditions are violated.

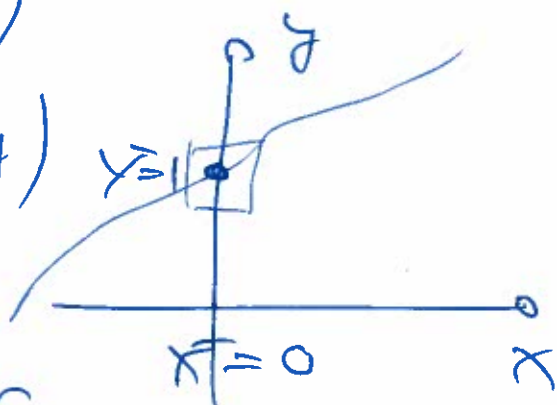
A pretty weak statement then....

Examples:

15

$$\textcircled{1} \quad y' = \underbrace{\sin(xy)}_{f(x,y)}; \quad y(0) = 1$$

$$\left\{ \begin{array}{l} f(x,y) = \sin(xy) \\ \frac{\partial f}{\partial y} = x \cos(xy) \end{array} \right.$$

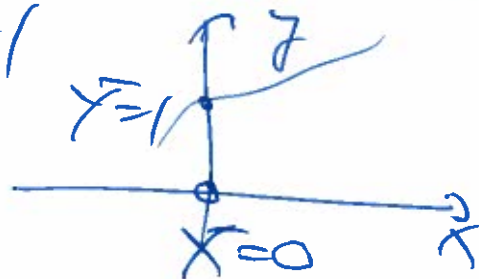


both continuous fcts of x & y
for all x & y

\Rightarrow unique soln. exists
in the vicinity of (x, y) .

$$\textcircled{2} \quad y' = \underbrace{y^2}_{f(x,y)}$$

$$y(0) = 1$$



$$\left. \begin{array}{l} f(x,y) = y^2 \\ \frac{\partial f}{\partial y} = 2y \end{array} \right\}$$

cont. fcts for
all values of
 x & y

\Rightarrow unique soln exists in

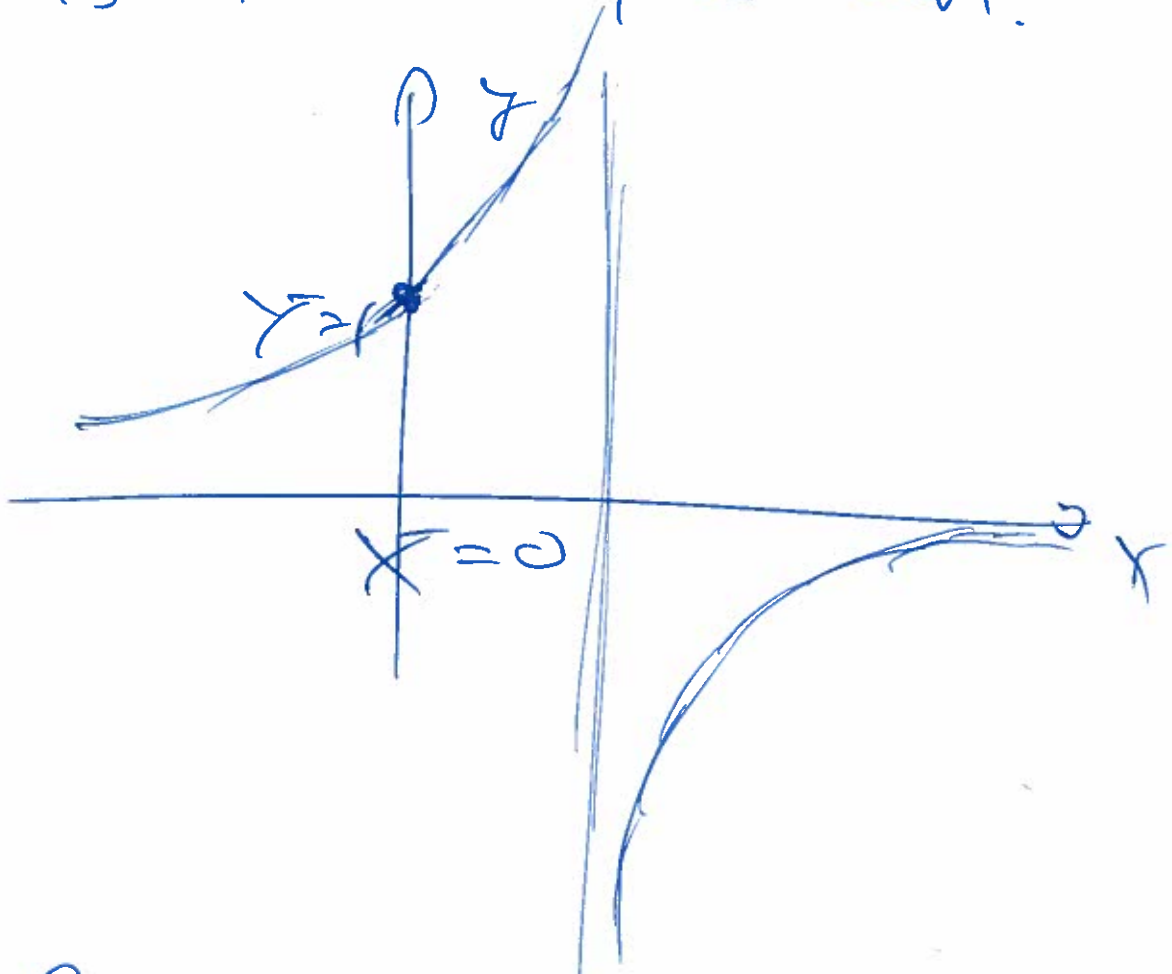
vicinity of $(0, 1)$.

(6)

In fact,

$$f(x) = \frac{1}{1-x} = (1-x)^{-1}$$

is that unique soln.



Soln only exists for $x < 1$

Existence and uniqueness theorem for *linear* 1st order ODEs

Consider the *linear* first-order ODE

$$\frac{dy}{dx} + p(x)y = q(x), \quad (3)$$

subject to the initial condition

$$y(X) = Y, \quad (4)$$

where the constants X and Y and the functions $p(x)$ and $q(x)$ are given.

Theorem

If the functions $p(x)$ and $q(x)$ are continuous functions in an interval I , and if $X \in I$ then there **exists exactly one** solution to the initial value problem defined by (3) and (4) in the entire interval I .

Notes:

- The statement is again easily generalised to higher-order ODEs.
- The theorem provides a “much more global” statement. In fact, if the functions $p(x)$ and $q(x)$ are “well-behaved” (no jumps, singularities, etc.) the theorem guarantees the existence of a unique solution for $x \in \mathbb{R}$.
- However, the statement still only applies to initial value problems!

This is a much stronger statement and explains in part why (some) mathematicians love (only) linear problems.

Examples:

(8)

$$\textcircled{1} \quad u' + \underbrace{x}_p(x) u = \underbrace{x}_q(x); \quad u(0) = 2$$

$p(x) = x$ } both are continuous
 $q(x) = x$ } fcts of x for
 $x \in \mathbb{R}$

\Rightarrow unique soln. exists
for $x \in \mathbb{R}$

$$u(x) = 1 + \exp\left(-\frac{1}{2}x^2\right)$$

$$\textcircled{2} \quad u' + \underbrace{\frac{1}{x}}_p(x) u = \underbrace{2}_q(x) + \mathbb{I}_c.$$

$p(x) = \frac{1}{x}$ } continuous in
 $q(x) = 2$ } two distinct intervals
 $I_1 = (-\infty, 0)$
 $I_2 = (0, \infty)$

⇒ Unique soln exists
in either of these
intervals!

9

In fact:

$$u(x) = x + \frac{A}{x}$$

is the (most) general soln.

It contains one constant, A ,
which is determined by
the IC.

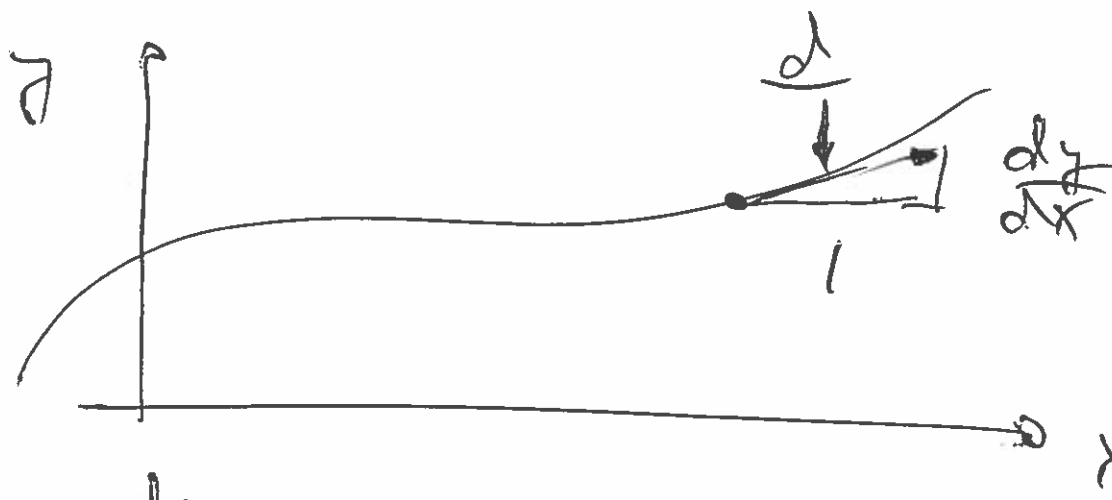
Note: In general the
soln. does indeed not
exist for $x = 0$.

First order ODEs

(10)

$$y' = f(x, y)$$

I Graphical approach



$\frac{dy}{dx}$ is the slope of the soln.

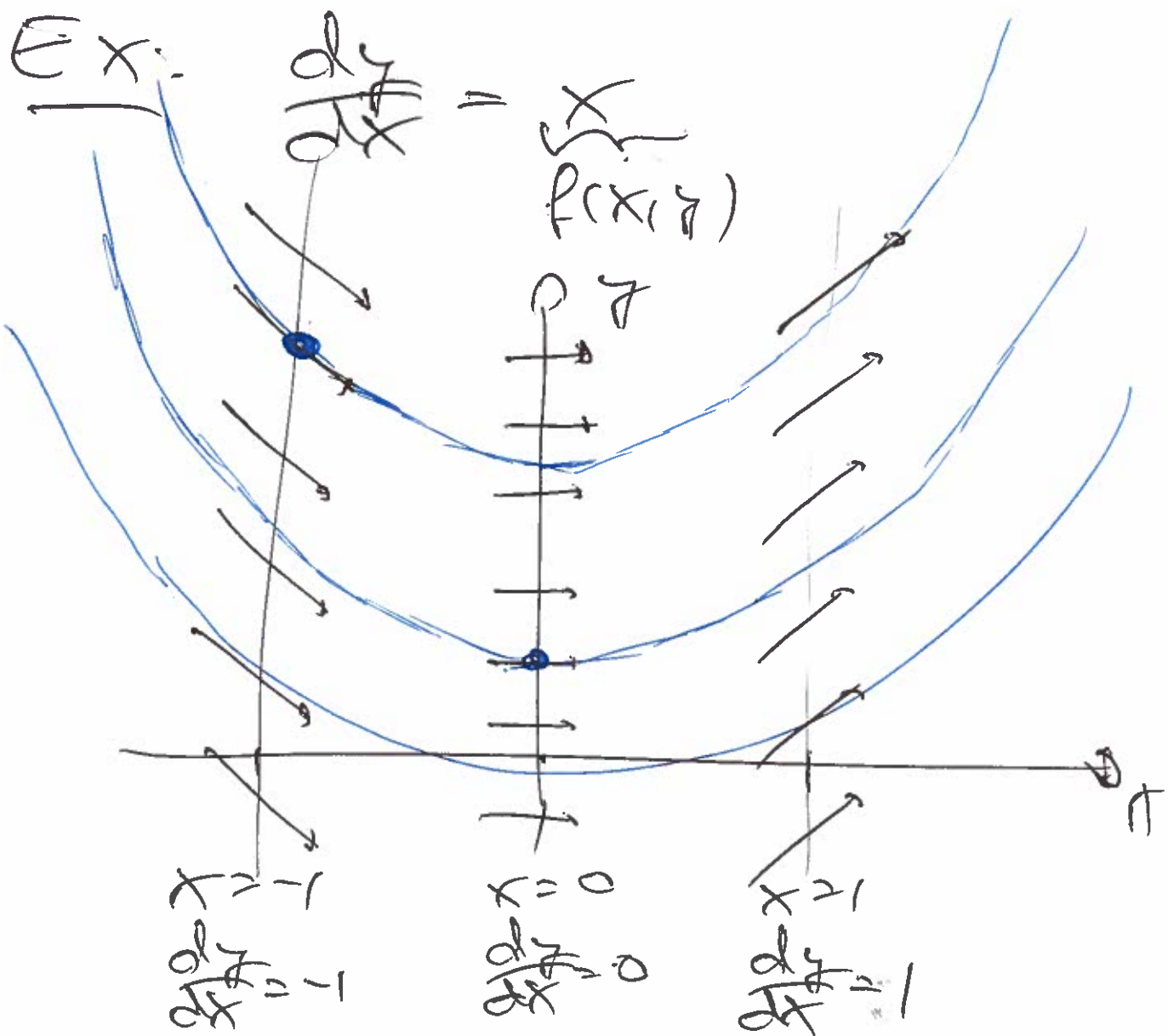
$f(x, y)$ defines the slope of solution curve(s).

Def: The "direction field" of the ODE is the set of all vectors that have the same direction as

$$\underline{d} = \begin{pmatrix} 1 \\ \frac{dy}{dx} \end{pmatrix} = \begin{pmatrix} 1 \\ f(x, y) \end{pmatrix}$$

Def: "Integral curves" are the

curves that are everywhere tangent to the direction field. These integral curves are solutions of the ODE.



E & U is obvious &

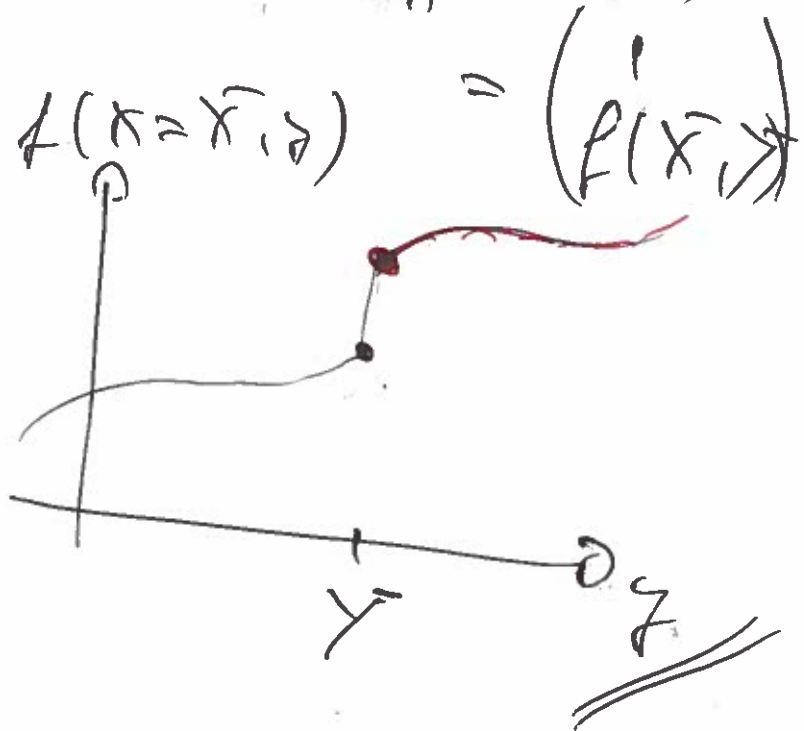
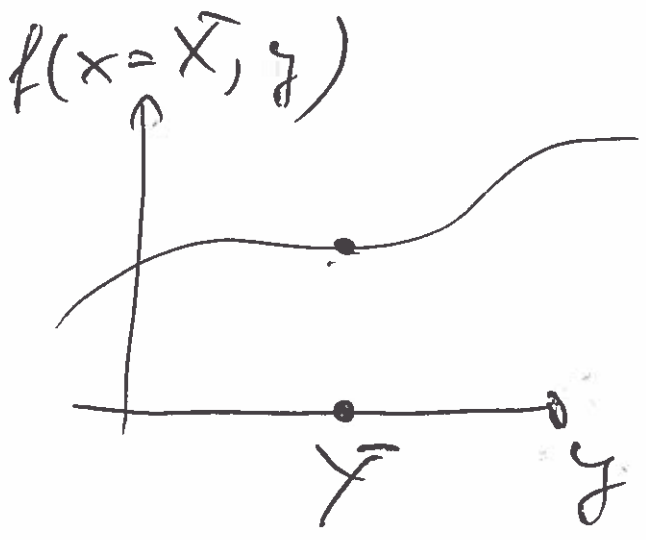
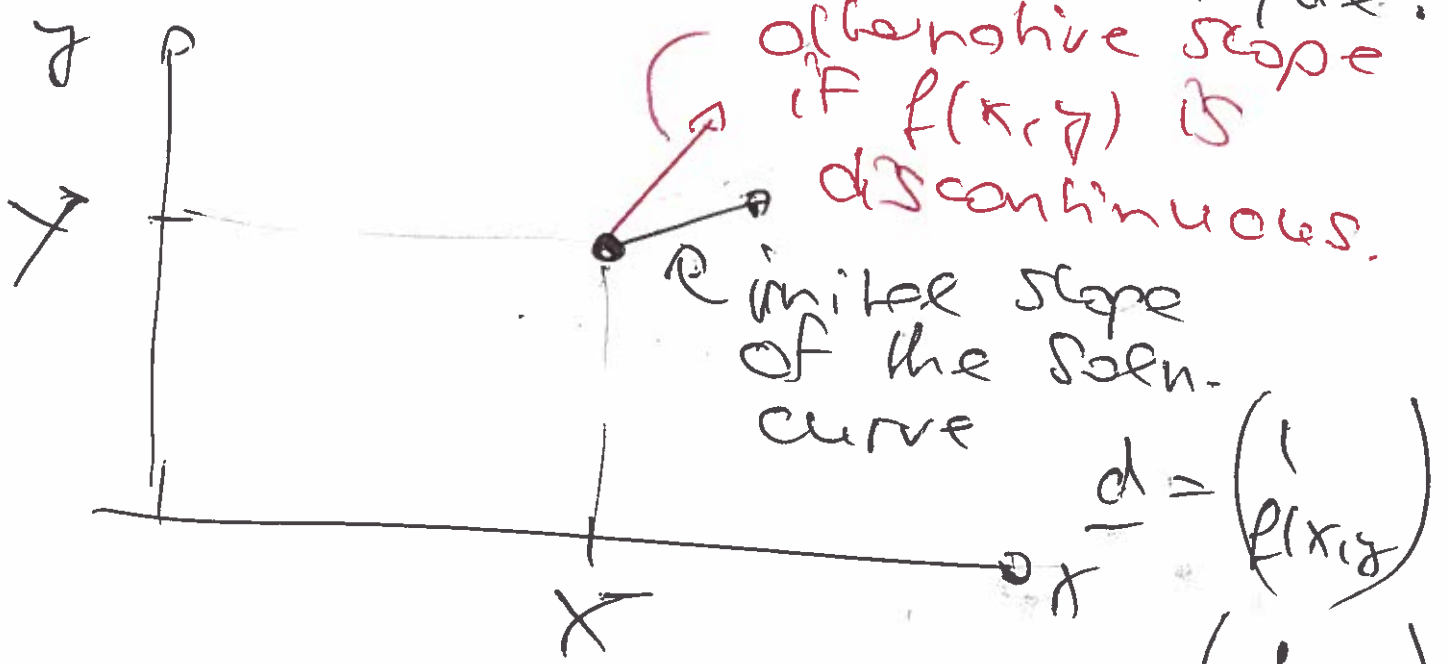
graphical solution illustrates the character of the solution.

In fact:

$$y = \frac{1}{2}x^2 + C$$

is the soln.

In fact: How can a solution starting from a given I.C. not be unique?



Observation:

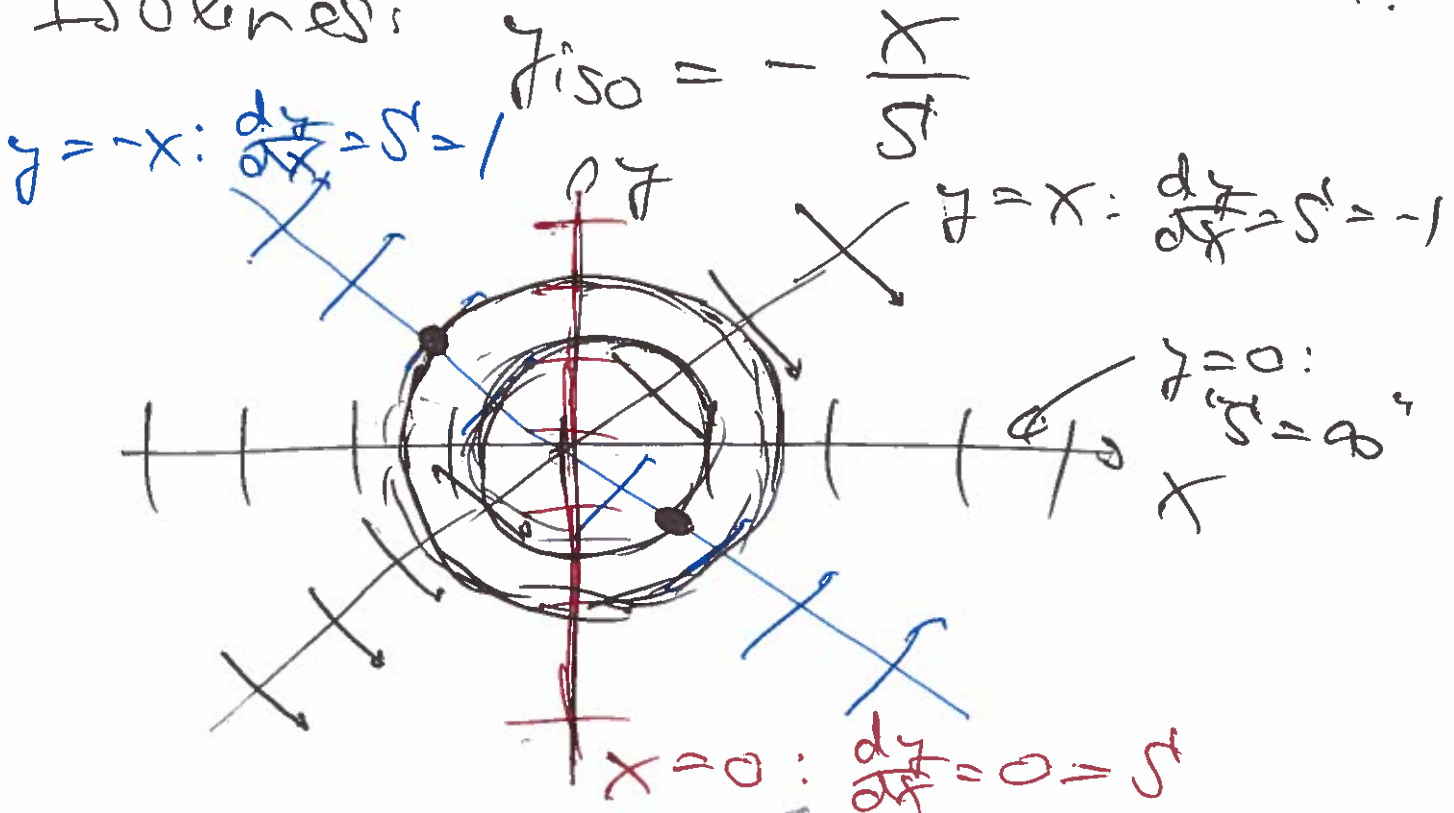
(13)

When sketching solns it is helpful to identify so-called iso-clines which are lines in $x-y$ plane where $\frac{dy}{dx} = \text{const.}$

Example:

$$\frac{dy}{dx} = \left[-\frac{x}{y} = f(x,y) = \sigma \right]_{\text{const.}}$$

Isoclines:



Solution: circular arcs $\frac{114}{(?)}$

In fact,

$$y = \pm \sqrt{R^2 - x^2}$$

is the general soln.

Const. R is determined
by the I.C.