

# Notes on XXX

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## 1 Introduction

It can be shown that

$$\widehat{C} = AB + \Delta C, \quad |C| \leq nu|A||B| + O(u^2). \quad (1)$$

Proving equation (1) is left as an exercise for the reader. For details on floating point arithmetic see [1].

If  $D = \text{diag}(d_i)$  then  $D^{-1} = \text{diag}(d_i^{-1})$ .

In general, we have

$$\min_{E \in \mathcal{E}} \|E\|_F = \min \left\{ \frac{\|r\|_2}{\|x\|_2}, \sigma_{\min}([A, R]) \right\}.$$

This modified formula requires the SVD of an  $m \times 2m$  matrix instead of an eigendecomposition of a symmetric  $m \times m$  matrix. We note that if an SVD of  $A$  is available, it can be exploited to reduce the cost of evaluating or estimating  $\sigma_{\min}([A, R])$ , but we will not go into the details.

**Lemma 1.1** *Let  $A \in \mathbb{C}^{m \times n}$  ( $m \geq n$ ) have the polar decomposition  $A = UH$ . Then*

$$\frac{\|A^*A - I\|}{\|A\|_2 + 1} \leq \|A - U\| \leq \|A^*A - I\|,$$

for any unitarily invariant norm  $\|\cdot\|$ .

**Proof.** Exercise.  $\square$

Lemma 1.1 relates  $A - U$  to the departure of the columns of  $A$  from orthogonality.

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## 1.1 Basic Linear Algebra Definitions

$\mathbb{R}^{m \times n}$  denotes the vector space of all real  $m \times n$  matrices.

$$A \in \mathbb{R}^{m \times n} \iff A = (a_{ij}) = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix}.$$

$\mathbb{R}^n$  denotes the vector space of real  $n$ -vectors. Generally, we use

capital letters	$A, B, C, \Delta, \Lambda$	for matrices,
lower case letters	$a_{ij}, b_{ij}, c_{ij}, \delta_{ij}, \lambda_{ij}$	for matrix elements,
lower case letters	$x, y, z, c, g, h$	for vectors,
lower case Greek letters	$\alpha, \beta, \gamma, \theta, \pi$	for scalars.

Basic matrix operations include:

$$\begin{aligned} C = A + B &\iff c_{ij} = a_{ij} + b_{ij} \\ C = \alpha A &\iff c_{ij} = \alpha a_{ij} \\ \underbrace{C}_{m \times p} = \underbrace{A}_{m \times n} \underbrace{B}_{n \times p} &\iff c_{ij} = \sum_{k=1}^n a_{ik} b_{kj} \\ C = A^T &\iff c_{ij} = a_{ji} \quad (A \in \mathbb{R}^{n \times n}) \\ C = A^* = A^H &\iff c_{ij} = \overline{a_{ji}} \quad (A \in \mathbb{C}^{n \times n}) \end{aligned}$$

The matrix

$$A = \begin{bmatrix} \cos \lambda & -\sin \lambda \\ \sin \lambda & \cos \lambda \end{bmatrix} \quad \lambda \neq (2k + 1)\pi,$$

has the principal logarithm

$$\log(A) = \begin{bmatrix} 0 & -\lambda \\ \lambda & 0 \end{bmatrix}.$$

If  $A, B \in \mathbb{R}^{n \times n}$  satisfy  $AB = I$  then  $B$  is the *inverse* of  $A$ , written  $B = A^{-1}$ . If  $A^{-1}$  exists  $A$  is *nonsingular*; otherwise  $A$  is *singular*.

## 2 Algorithm

We now state our algorithm.

**Algorithm 1** ( $F = \mathbf{F}(t, A, B, \text{balance})$ ) *Given*  $A \in \mathbb{C}^{n \times n}$ ,  $B \in \mathbb{C}^{n \times n_0}$ ,  $t \in \mathbb{C}$ , and a tolerance  $\text{tol}$ , *this algorithm produces an approximation*  $F \approx e^{tA}B$ . *The logical variable*  $\text{balance}$  *indicates whether or not to apply balancing.*

- 1 if  $\text{balance}$
- 2  $\tilde{A} = D^{-1}AD$
- 3 if  $\|\tilde{A}\|_1 < \|A\|_1$ ,  $A = \tilde{A}$ ,  $B = D^{-1}B$ , else  $\text{balance} = \text{false}$ , end
- 4 end
- 5  $\mu = \text{trace}(A)/n$

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6  A very long line, a very long line,
   a very long line, a very long line. Continuation is not numbered.
7   $A = A - \mu I$ 
8  if  $t\|A\|_1 = 0$ 
9      $m_* = 0, s = 1$   % The case  $tA = 0$ .
10 else
11      $[m_*, s] = \text{parameters}(tA, \text{tol})$ 
12 end
13  $F = B, \eta = e^{t\mu/s}$ 
14 for  $i = 1:s$ 
15      $c_1 = \|B\|_\infty$ 
16     for  $j = 1:m_*$ 
17          $B = tAB/(sj), c_2 = \|B\|_\infty$ 
18          $F = F + B$ 
19         if  $c_1 + c_2 \leq \text{tol}\|F\|_\infty$ , break, end
20          $c_1 = c_2$ 
21     end
22      $F = \eta F, B = F$ 
23 end
24 if balance,  $F = DF$ , end

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Line 7 shifts by the mean of the eigenvalues. Line 19 tests for convergence.

## References

- [1] Nicholas J. Higham. *Accuracy and Stability of Numerical Algorithms*. Society for Industrial and Applied Mathematics, Philadelphia, PA, USA, second edition, 2002.