

Structured Mapping Problems for Automorphism Groups and Lie and Jordan Algebras

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Structured Mapping Problems

Given a class of structured matrices \mathbb{S} ,

1: For which vectors x, b is it possible to find some $A \in \mathbb{S}$ such that $Ax = b$?

2: Determine the set $\mathcal{S} = \{A \in \mathbb{S} : Ax = b\}$.

Motivation: *Structured backward errors for structured linear systems and structured eigenproblems.*

Structured Backward Errors

Let (x, λ) be an approximate eigenpair of A .

The backward error of (x, λ) is a measure of the smallest perturbation E such that

$$(A + E)x = \lambda x \iff Ex = r,$$

where $r = (\lambda I - A)x$.

The **structured** backward error is

$$\min\{\|E\| : Ex = r, E \in \mathcal{S}\}.$$

Background

Given nonsingular M and $\mathbb{K} = \mathbb{R}$ or \mathbb{C} ,

$$\langle x, y \rangle_M = \begin{cases} x^T M y, & \text{real or complex bilinear forms,} \\ x^* M y, & \text{sesquilinear forms.} \end{cases}$$

Recall **adjoint** A^* of $A \in \mathbb{K}^{n \times n}$ wrt $\langle \cdot, \cdot \rangle_M$ defined by

$$\langle Ax, y \rangle_M = \langle x, A^* y \rangle_M \quad \forall x, y \in \mathbb{K}^n.$$

The adjoint with respect to $\langle \cdot, \cdot \rangle_M$ is **involutory** if

$$(A^*)^* = A, \quad \forall A \in \mathbb{K}^{n \times n}.$$

Structured Matrices

Associated to $\langle \cdot, \cdot \rangle_{\mathbf{M}}$ in \mathbb{K}^n are three important classes of matrices:

► Automorphism group:

$$\mathbb{G} = \{G \in \mathbb{K}^{n \times n} : \langle Gx, Gy \rangle_{\mathbf{M}} = \langle x, y \rangle_{\mathbf{M}}\} = \{G : G^{\star} = G^{-1}\}.$$

► Jordan algebra

$$\mathbb{J} = \{S \in \mathbb{K}^{n \times n} : \langle Sx, y \rangle_{\mathbf{M}} = \langle x, Sy \rangle_{\mathbf{M}}\} = \{S : S^{\star} = S\}.$$

► Lie algebra

$$\mathbb{L} = \{L \in \mathbb{K}^{n \times n} : \langle Lx, y \rangle_{\mathbf{M}} = -\langle x, Ly \rangle_{\mathbf{M}}\} = \{L : L^{\star} = -L\}.$$

Consider $A \in \mathbb{G}, \mathbb{J}$ or \mathbb{L} arising from orthosymmetric $\langle \cdot, \cdot \rangle_{\mathbf{M}}$.

Orthosymmetric Scalar Products

$\langle \cdot, \cdot \rangle_{\mathbf{M}}$ is **orthosymmetric** iff it satisfies one of the following properties:

1. $\langle x, y \rangle_{\mathbf{M}} = 0 \Leftrightarrow \langle y, x \rangle_{\mathbf{M}} = 0, \forall x, y \in \mathbb{K}^n.$
2. $\mathbb{K}^{n \times n} = \mathbf{L} \oplus \mathbf{J}.$
3. $M^T = \pm M$ for bilinear forms; $M^* = \alpha M$ with $\alpha \in \mathbb{C}, |\alpha| = 1$ for sesquilinear forms.
4. $(A^*)^* = A, \forall A \in \mathbb{K}^{n \times n}.$

Up to a scalar multiple there are

only three distinct types of orthosymmetric $\langle \cdot, \cdot \rangle_{\mathbf{M}}$:
symmetric and skew-symmetric bilinear, and Hermitian sesquilinear.

Existence Problem for Lie/Jordan Algebras

Given a class of structured matrices $\mathbb{S} = \mathbb{J}, \mathbb{L}$,

For which nonzero vectors x, b is it possible to find some $A \in \mathbb{S}$ such that $Ax = b$?

Results known for:

- ▶ Symmetric and Hermitian matrices.
[J.-G. Sun, Numer. Math. (65):1993]
- ▶ Persymmetric and skew-symmetric matrices.
[S. Rump, SIMAX (25):2003]

Existence Results for Lie/Jordan Algebras

- ▶ Symmetric matrices: $\mathbb{J} = \{A \in \mathbb{R}^{n \times n} : A = A^T\}$,
Persymmetric matrices: $\mathbb{J} = \{A \in \mathbb{R}^{n \times n} : RA = (RA)^T\}$,

$$\{A \in \mathbb{J} : Ax = b\} \neq \emptyset \text{ for all } x, b \in \mathbb{R}^n, x \neq 0.$$

- ▶ Skew-symmetric matrices: $\mathbb{L} = \{A \in \mathbb{R}^{n \times n} : A = -A^T\}$.

$$b^T x = 0 \Rightarrow \{A \in \mathbb{L} : Ax = b, \} \neq \emptyset.$$

- ▶ Hermitian matrices: $\mathbb{J} = \{A \in \mathbb{C}^{n \times n} : A = A^*\}$.

$$\{A \in \mathbb{J} : Ax = b\} \neq \emptyset \Leftrightarrow x^* b \in \mathbb{R}.$$

Extend these results to all \mathbb{L} and \mathbb{J} of any orthosymmetric $\langle \cdot, \cdot \rangle_M$.

Existence Theorem for Jordan Algebras

\mathbb{J} : Jordan algebra of any orthosymmetric $\langle \cdot, \cdot \rangle_{\mathbb{M}}$ on \mathbb{K}^n ,
 x, b given vectors in \mathbb{K}^n , $x \neq 0$, define

$$\mathcal{J} = \{A \in \mathbb{J} : Ax = b\}.$$

Theorem 1

$$\mathcal{J} \neq \emptyset \Leftrightarrow \begin{cases} x, b \in \mathbb{K}^n, x \neq 0 & \text{(symmetric bilinear)} \\ \langle b, x \rangle_{\mathbb{M}} = 0 & \text{(skew-symmetric bilinear)} \\ \langle b, x \rangle_{\mathbb{M}} \in \mathbb{R} & \text{(Hermitian sesquilinear)} \\ \langle b, x \rangle_{\mathbb{M}} \in i\mathbb{R} & \text{(skew-Hermitian sesquilinear)}. \end{cases}$$

Proof. (\Rightarrow) In all cases we have

$$A \in \mathcal{J} \Rightarrow \langle b, x \rangle_{\mathbb{M}} = \langle Ax, x \rangle_{\mathbb{M}} = \langle x, Ax \rangle_{\mathbb{M}} = \langle x, b \rangle_{\mathbb{M}}.$$

Proof of Theorem 1 (\Leftarrow)

$$\text{Let } B := \begin{cases} bw^T M + (bw^T M)^* P & \text{(bilinear),} \\ bw^* M + (bw^* M)^* P & \text{(sesquilinear),} \end{cases}$$

$$\text{where } P := \begin{cases} I - xw^T M & \text{(bilinear),} \\ I - xw^* M & \text{(sesquilinear),} \end{cases}$$

and $w \in \mathbb{K}^n$ s.t. $\langle w, x \rangle_M = 1$.

$Bx = b$ always holds.

$$\left. \begin{array}{l} \text{Symmetric bilinear:} \\ \text{Skew-symmetric bilinear:} \\ \text{Hermitian sesquilinear:} \\ \text{Skew-Hermitian sesquilinear:} \end{array} \right\} \begin{array}{l} x, b \in \mathbb{K}^n, x \neq 0 \\ \langle b, x \rangle_M = 0 \\ \langle b, x \rangle_M \in \mathbb{R} \\ \langle b, x \rangle_M \in i\mathbb{R}. \end{array} \Rightarrow B \in \mathbb{J}.$$

Characterization Results for \mathbb{L}

For given $x, b \in \mathbb{K}^n$, $x \neq 0$ determine $\mathcal{S} = \{A \in \mathbb{J} : Ax = b\}$.

► Symmetric: $\mathbb{J} = \{A \in \mathbb{R}^{n \times n} : A = A^T\}$ [Sun,93]

$$\mathcal{S} = \left\{ \frac{bx^T}{x^T x} + \frac{x^T b}{x^T x} P_x + P_x H P_x, H \in \mathbb{J} \right\}, P_x = I - \frac{xx^T}{x^T x}.$$

Same characterization for complex symmetric matrices when x non-isotropic.

Homogeneous Problem

\mathbb{J} : Jordan algebra of an orthosymmetric $\langle \cdot, \cdot \rangle_M$ on \mathbb{K}^n .

x, b given vectors in \mathbb{K}^n , $x \neq 0$ and $w \in \mathbb{K}^n$ s.t. $\langle w, x \rangle_M = 1$.

Lemma 1 $\{A \in \mathbb{J} : Ax = 0\} = \{P^*SP : S \in \mathbb{J}\},$

where

$$P = \begin{cases} I - xw^T M & (\text{bilinear}), \\ I - xw^* M & (\text{sesquilinear}). \end{cases}$$

Hence, if $A, B \in \mathbb{J}$ s.t. $Ax = Bx = b$, then $(A - B)x = 0$ and

Lemma 1 \Rightarrow

$$A = B + P^*SP \text{ for some } S \in \mathbb{J}.$$

Mapping Problem for Jordan Algebras

\mathbb{J} : Jordan algebra of an orthosymmetric $\langle \cdot, \cdot \rangle_M$ on \mathbb{K}^n .
 x, b given vectors in \mathbb{K}^n , $x \neq 0$ and $w \in \mathbb{K}^n$ s.t. $\langle w, x \rangle_M = 1$.

Theorem 2 *If $\{A \in \mathbb{J} : Ax = b\} \neq \emptyset$ then*

$$\{A \in \mathbb{J} : Ax = b\} = \{B + P^*SP : S \in \mathbb{J}\},$$

where

$$B = \begin{cases} bw^T M + (bw^T M)^* P & \text{(bilinear),} \\ bw^* M + (bw^* M)^* P & \text{(sesquilinear),} \end{cases}$$

$$P = \begin{cases} I - xw^T M & \text{(bilinear),} \\ I - xw^* M & \text{(sesquilinear).} \end{cases}$$

Existence Theorem for Automorphism Groups

\mathbb{G} : automorphism group of an orthosymmetric $\langle \cdot, \cdot \rangle_{\mathbf{M}}$ on \mathbb{K}^n .
 x, b : given nonzero vectors in \mathbb{K}^n .

Theorem 3

$$\{A \in \mathbb{G} : Ax = b\} \neq \emptyset \iff q(x) = q(b),$$

where $q(z) = \langle z, z \rangle_{\mathbf{M}}$.

Proof.

(\Rightarrow) $A \in \mathbb{G}$ s.t. $Ax = b \Rightarrow q(x) = q(Ax) = q(b)$.

(\Leftarrow) Nontrivial.

G-Reflectors

A \mathbb{G} -reflector is a matrix in \mathbb{G} of the form

$$(1) \quad G = \begin{cases} I + \beta uu^T M & \text{(bilinear),} \\ I + \beta uu^* M & \text{(sesquilinear),} \end{cases}$$

where $0 \neq \beta \in \mathbb{K}$ and $0 \neq u \in \mathbb{K}^n$.

Theorem 4 (G-Reflector Mapping Theorem) *For distinct nonzero $x, b \in \mathbb{K}^n$, there exists a \mathbb{G} -reflector G s.t. $Gx = b$ iff $q_M(x) = q_M(b)$ and $\langle b - x, x \rangle_M \neq 0$.*

When G exists, it is unique and is specified by taking $u = b - x$ and $\beta = 1/\langle u, x \rangle_M$ in (1).

Two \mathbb{G} -Reflector Mapping Theorem

Theorem 5 For any $0 \neq x, b \in \mathbb{K}^n$ s.t. $q(x) = q(b)$, there exists $A \in \mathbb{G}$ such that $Ax = b$, where A is the product of at most two \mathbb{G} -reflectors.

Proof. Define $\mathcal{F}_x := \{y \in \mathbb{K}^n, \langle y - x, x \rangle = 0\}$.

$b \notin \mathcal{F}_x$: \exists single \mathbb{G} -reflector mapping x to b .

$b \in \mathcal{F}_x$: need a third stepping point z such that $q(z) = q(x) = q(b)$ and $z \notin \mathcal{F}_x \cup \mathcal{F}_b$.

$$x \xrightarrow{G_1} z \xrightarrow{G_2^{-1}} b.$$

Can show that there always exists such z .

Isotropic/Non-Isotropic Vectors

- ▶ x is non-isotropic $\iff x \notin x_{\mathbf{M}}^{\perp} \iff \mathbb{K}^n = \text{span}\langle x \rangle \oplus x_{\mathbf{M}}^{\perp}$.
- ▶ x is isotropic $\iff x \in x_{\mathbf{M}}^{\perp} \iff \text{span}\langle x \rangle \subseteq x_{\mathbf{M}}^{\perp}$,

Lemma 2 Suppose $A \in \mathbb{G}$ and $Ax = b$. Then $A(x_{\mathbf{M}}^{\perp}) = b_{\mathbf{M}}^{\perp}$.

$$\mathbb{K}^n = \left[\begin{array}{ccc} \text{span}\langle x \rangle & \xrightarrow{A} & \text{span}\langle b \rangle \\ \oplus & & \oplus \\ x_{\mathbf{M}}^{\perp} & \xrightarrow{A} & b_{\mathbf{M}}^{\perp} \end{array} \right] = \mathbb{K}^n$$

Non-Isotropic Case

\mathbb{G} : automorphism group of an orthosymmetric $\langle \cdot, \cdot \rangle_M$ on \mathbb{K}^n .
 x, b : given nonzero vectors in \mathbb{K}^n .

Theorem 6 *If $q(x) = q(b) \neq 0$ then*

$$\{A \in \mathbb{G} : Ax = b\} = \{S_{b,x} + Q(I - P_x) : Q \in \mathbb{G}, QP_x = P_bQ\},$$

where

$$P_y := \begin{cases} yy^T M/q(y) & (\text{bilinear}), \\ yy^* M/q(y) & (\text{sesquilinear}), \end{cases}$$

$$S_{b,x} := \begin{cases} bx^T M/q(x) & (\text{bilinear}), \\ bx^* M/q(x) & (\text{sesquilinear}). \end{cases}$$

Isotropic Case

Restrict to particular orthosymmetric $\langle \cdot, \cdot \rangle_M$:
 M must be either

1. **real** symmetric **orthogonal**,
2. skew-symmetric,
3. Hermitian **unitary**,
4. skew-Hermitian **unitary**.

Useful property:

$$q_M(z) = 0 \Leftrightarrow \begin{cases} q_{M^{-1}}(\bar{z}) = 0 & \text{(bilinear),} \\ q_{M^{-1}}(z) = 0 & \text{(sesquilinear).} \end{cases}$$

Modified Structured Problem

For given nonzero $x, b \in \mathbb{K}^n$ s.t. $q(x) = q(b) = 0$, determine the “slightly” modified set

$$\tilde{\mathcal{G}} = \left\{ A \in \mathbb{G} : Ax = b, A(M^{-1}\bar{x}) = \begin{pmatrix} x^*x \\ b^*b \end{pmatrix} (M^{-1}\bar{b}) \right\}.$$

We need rank-2 matrices:

$$\tilde{P}_x := \frac{xx^* + (xx^*)^\star}{x^*x}, \quad \tilde{S}_{b,x} := \frac{bx^*}{x^*x} + \frac{(xb^*)^\star}{b^*b}.$$

Can show that

$$\tilde{\mathcal{G}} = \left\{ \tilde{S}_{b,x} + Q(I - \tilde{P}_x) : Q \in \mathbb{G}, Q\tilde{P}_x = \tilde{P}_bQ \right\}.$$

Isotropic Case

Let $0 \neq x, b \in \mathbb{K}^n$ be given vectors s.t. $q(x) = q(b) = 0$ and define

$$\mathcal{G} := \{A \in \mathbb{G} : Ax = b\}.$$

Can show that for any $A \in \mathcal{G}$, there exist two \mathbb{G} -reflectors G_1, G_2 s. t. $\tilde{A} = G_2 G_1 A$ satisfies

$$\tilde{A}x = b \quad \text{and} \quad \tilde{A}(M^{-1}\bar{x}) = \begin{pmatrix} x^*x \\ b^*b \end{pmatrix} (M^{-1}\bar{b}).$$

Then

$$\mathcal{G} = \{G_1^{-1}G_2^{-1} \left(\tilde{S}_{b,x} + Q(I - \tilde{P}_x) \right) : Q \in \mathbb{G}, Q\tilde{P}_x = \tilde{P}_bQ\},$$

where

$$\tilde{P}_x := \frac{xx^* + (xx^*)^*}{x^*x}, \quad \tilde{S}_{b,x} := \frac{bx^*}{x^*x} + \frac{(xb^*)^*}{b^*b}.$$

Summary

Given a class of structured matrices \mathbb{S} ,

(1): For which nonzero vectors x, b is it possible to find some $A \in \mathbb{S}$ such that $Ax = b$?

(2): Determine the set $\mathcal{S} = \{A \in \mathbb{S} : Ax = b\}$.

- ▶ Consider $\mathbb{S} = \mathbb{G}, \mathbb{J}$ or \mathbb{L} of any orthosymmetric $\langle \cdot, \cdot \rangle_{\mathbb{M}}$.
- ▶ Solved (1) and (2) for any \mathbb{L} and \mathbb{J} (linear structures).
- ▶ Solved
 - (1) for all \mathbb{G} (nonlinear structures).
 - (2) for all \mathbb{G} when x, b are non-isotropic.
- ▶ For isotropic x, b , solved (2) for a particular class of orthosymmetric $\langle \cdot, \cdot \rangle_{\mathbb{M}}$.