

## MECHANICS

### Kinematics

Motion constant acceleration

$$\mathbf{v} = \mathbf{u} + \mathbf{f}t, \quad \mathbf{s} = \mathbf{u}t + \frac{1}{2}\mathbf{f}t^2 = \frac{1}{2}(\mathbf{u} + \mathbf{v})t$$

$$\mathbf{v}^2 = \mathbf{u}^2 + 2\mathbf{f} \cdot \mathbf{s}$$

General solution of  $\frac{d^2x}{dt^2} = -\omega^2x$  is

$$x = a \cos \omega t + b \sin \omega t = R \sin(\omega t + \phi)$$

where  $R = \sqrt{a^2 + b^2}$  and  $\cos \phi = a/R$ ,  $\sin \phi = b/R$ .

In polar coordinates the velocity is  $(\dot{r}, r\dot{\theta}) = \dot{r}\mathbf{e}_r + r\dot{\theta}\mathbf{e}_\theta$  and the acceleration is

$$\left[ \ddot{r} - r\dot{\theta}^2, r\ddot{\theta} + 2\dot{r}\dot{\theta} \right] = (\ddot{r} - r\dot{\theta}^2)\mathbf{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\mathbf{e}_\theta.$$

### Centres of mass

The following results are for uniform bodies:

hemispherical shell, radius $r$	$\frac{1}{3}r$	from centre
hemisphere, radius $r$	$\frac{3}{8}r$	from centre
right circular cone, height $h$	$\frac{3}{4}h$	from vertex
arc, radius $r$ and angle $2\theta$	$(r \sin \theta)/\theta$	from centre
sector, radius $r$ and angle $2\theta$	$(\frac{2}{3}r \sin \theta)/\theta$	from centre

### Moments of inertia

1. The moment of inertia of a body of mass  $m$  about an axis  $= I + mh^2$ , where  $I$  is the moment of inertia about the parallel axis through the mass-centre and  $h$  is the distance between the axes.
2. If  $I_1$  and  $I_2$  are the moments of inertia of a lamina about two perpendicular axes through a point  $O$  in its plane, then its moment of inertia about the axis through  $O$  perpendicular to its plane is  $I_1 + I_2$ .
3. The following moments of inertia are for uniform bodies about the axes stated:

rod, length $\ell$ , through mid-point, perpendicular to rod	$\frac{1}{12}m\ell^2$
hoop, radius $r$ , through centre, perpendicular to hoop	$mr^2$
disc, radius $r$ , through centre, perpendicular to disc	$\frac{1}{2}mr^2$
sphere, radius $r$ , diameter	$\frac{2}{5}mr^2$

### Work done

$$W = \int_{t_A}^{t_B} \mathbf{F} \cdot \frac{d\mathbf{r}}{dt} dt.$$